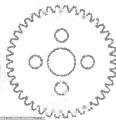


# Activity 3 – Gear Ratio



## Vocabulary

- gear increaser
- gear ratio
- gear reduction

## Materials

- TETRIX PRIME Starter Set
- Painter's tape
- Gears Resource Page
- "Gear Ratio Data Sheet"



## Objective

You will learn how gear ratio affects the number of rotations of the servo required to travel a distance.

## Procedure

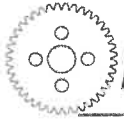
1. If you have not already done so, follow the instructions in the *Builder's Guide* to assemble the Wheelie Bot robot.
2. Review the information on the "Gears Resource Page."
3. Locate the two-meter distance marked by your instructor for this activity. If this has not been done, obtain permission to use painter's tape to mark a distance of two meters on the floor.
4. One student should be the driver and one student the recorder. The driver should slowly drive the robot the two meters while the recorder counts the number of times the servo shaft rotates. Record this number on the "Gear Ratio Data Sheet."
5. The driver and the recorder should change duties. The driver should slowly drive the robot the two meters while the recorder counts the number of times the axle on the wheel rotates. Record this number on the "Gear Ratio Data Sheet."
6. Remove the servo and place a large gear on the axle with the wheel. Add a small gear to the servo and relocate the servo to mesh the gears. You will now have a gear drive robot. (figure 3)
7. The driver should slowly drive the robot the two meters while the recorder counts the number of times the servo shaft rotates. Record this number on the "Gear Ratio Data Sheet."
8. The driver and the recorder should exchange duties. The driver should slowly drive the robot the two meters while the recorder counts the number of times the axle on the wheel rotates. Record this number on the "Gear Ratio Data Sheet."
9. Exchange the position of the gears by placing the larger gear on the servo and the smaller gear on the wheel axle. (figure 4)
10. The driver should slowly drive the robot the two meters while the recorder counts the number of times the servo shaft rotates. Record this number on the "Gear Ratio Data Sheet."
11. The driver and the recorder should change duties. The driver should slowly drive the robot the two meters while the recorder counts the number of times the axle on the wheel rotates. Record this number on the "Gear Ratio Data Sheet."

figure 3



figure 4





# Activity 3 – Gear Ratio

---

12. Complete the remaining information on the “Gear Ratio Data Sheet.”
13. Disassemble the robot and return the TETRIX PRIME parts to the storage container.

## Troubleshooting

- Make sure the gears turn freely and do not bind against the beam. Loosen the setscrew and place a small amount of clearance between the gears and the beam.
- Make sure the gears mesh together correctly. The spacing for the holes in the beams should make them mesh properly.
- Make sure the gears align correctly. Adjust the spacing using the setscrew if needed.