Get a Grip Data Sheet

- 1. What is the maximum height that the gripper can reach?
- 2. Suggest ways to increase the height that the robot can reach. Draw a sketch if necessary.
- 3. What is the maximum distance to the right or left that the robot can reach?
- 4. Suggest ways to increase the distance to the right or left that the robot can reach. Draw a sketch if necessary.
- 5. Hypothesize what consequences might result from changing the reach distance of the gripper.
- 6. How do the number of joints and the structure of a manipulator affect the work envelope of the robot?