

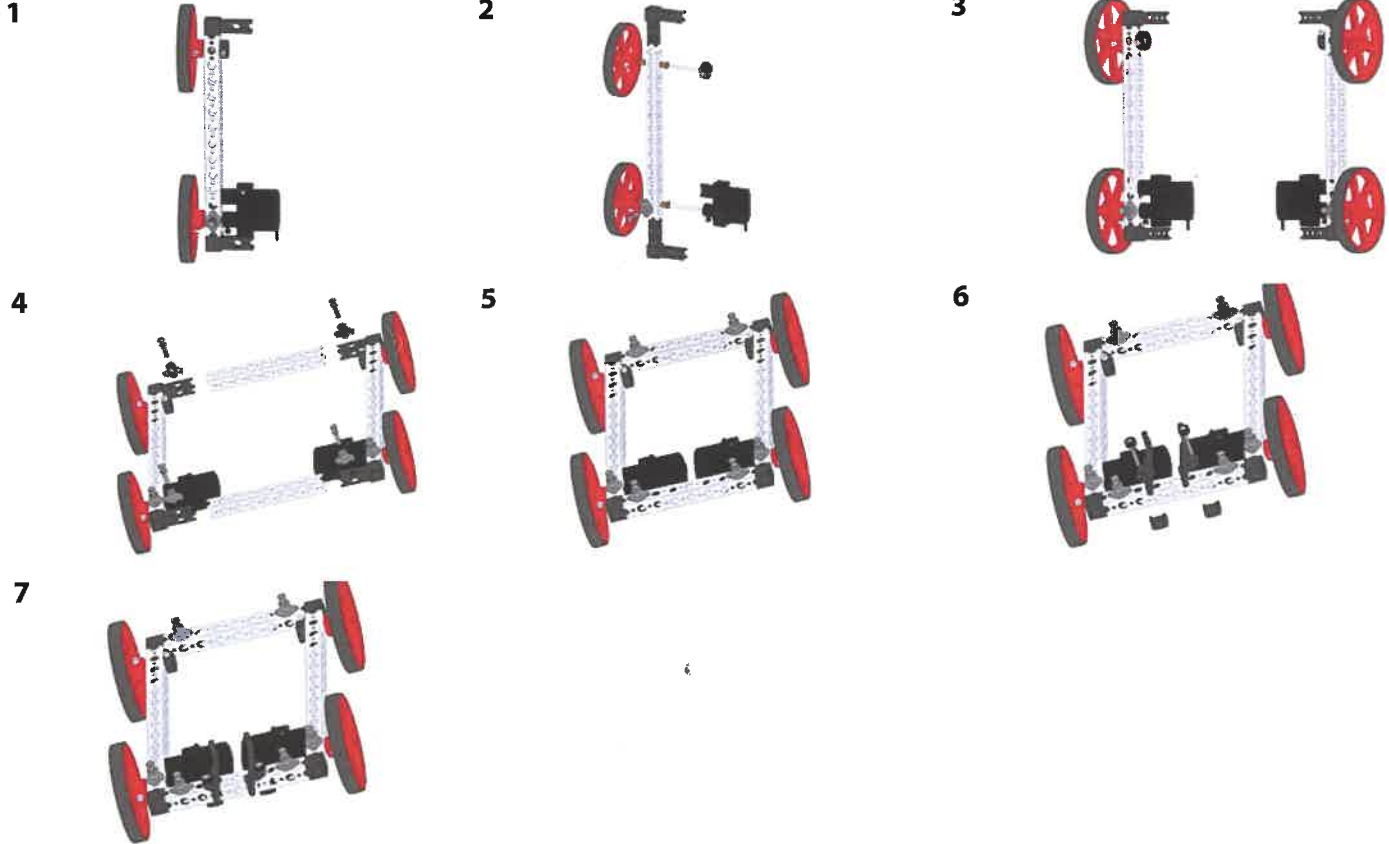
Activity 6 – Wheel Options

Objective

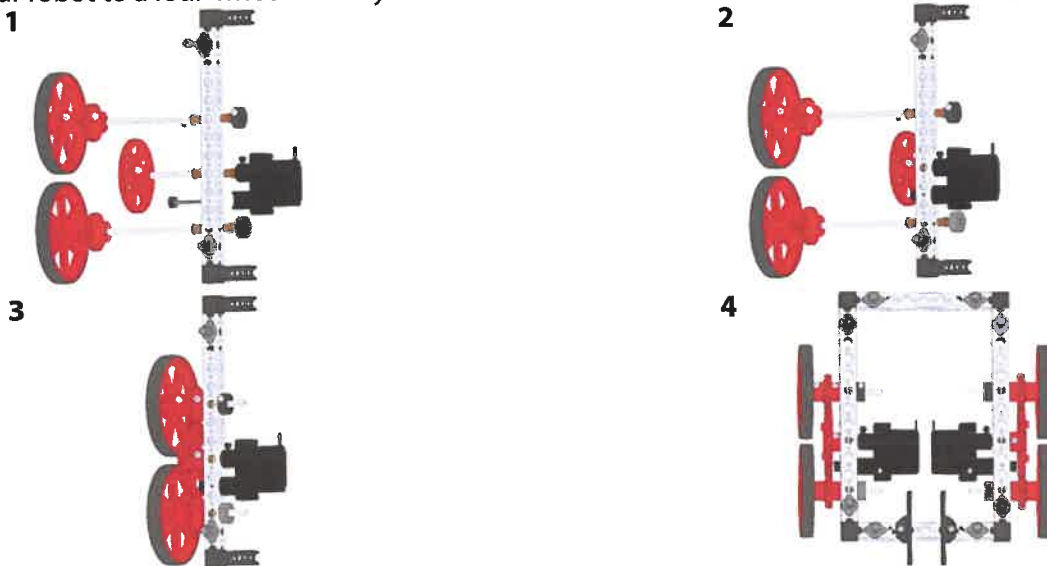
Construct a four-wheel robot to learn about the friction of wheels during turns.

Procedure

1. Construct a four-wheel robot with two driving wheels.



2. Test the performance of your robot and record information on the “Wheel Options Data Sheet.”
3. Modify your robot to a four-wheel drive system.



4. Test the performance of your robot and record the information on the “Wheel Options Data Sheet.”